

Deforming the Oscillator: Iterative Phases over Parametrizable Closed Paths

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Music, Math and Computation Reading Group

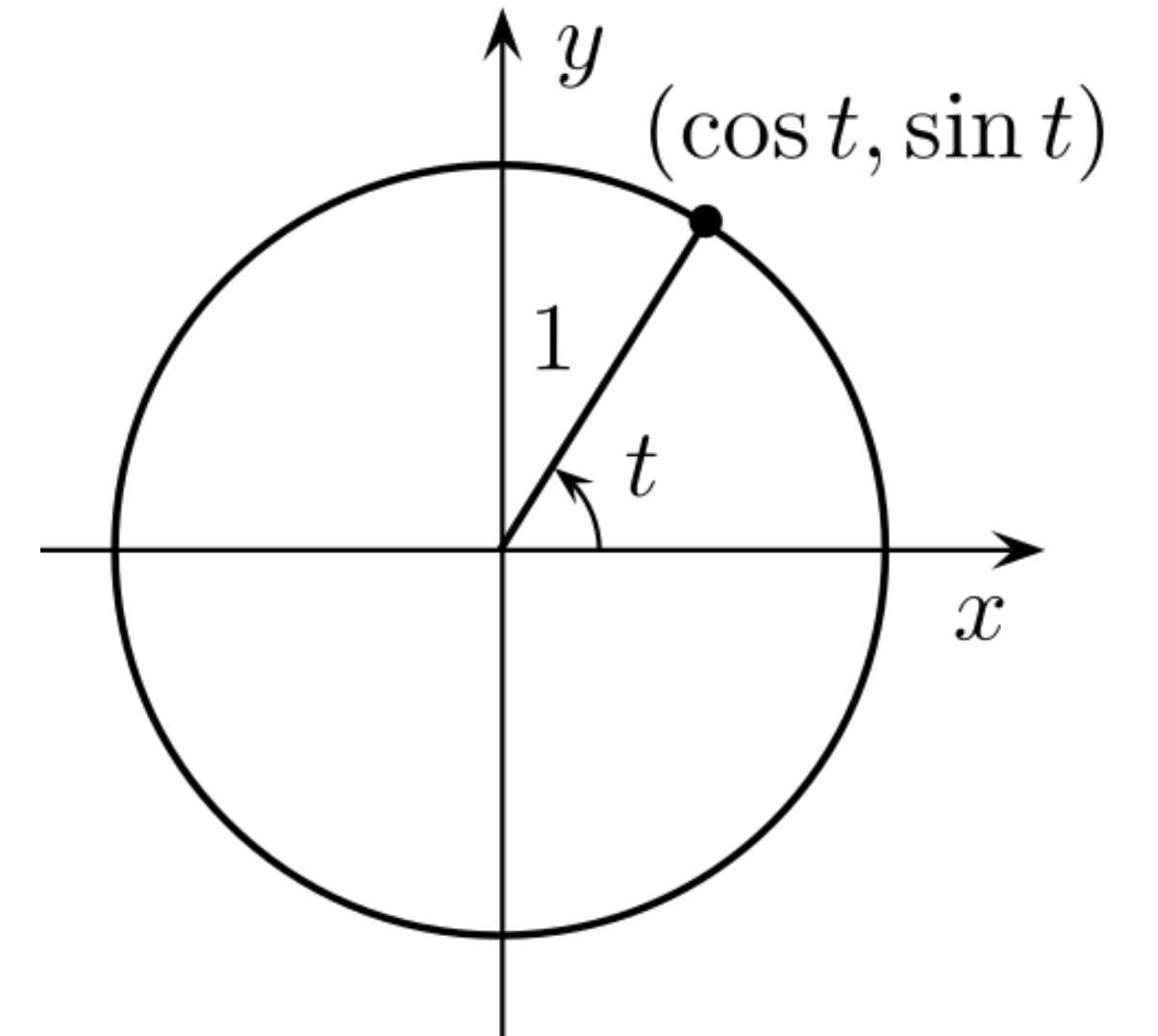
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The unit circle can be parameterized by the function

$$o : I \rightarrow S^1$$

$$o(t) = x + iy = \cos(2\pi t) + i \sin(2\pi t) = e^{2\pi i t}$$

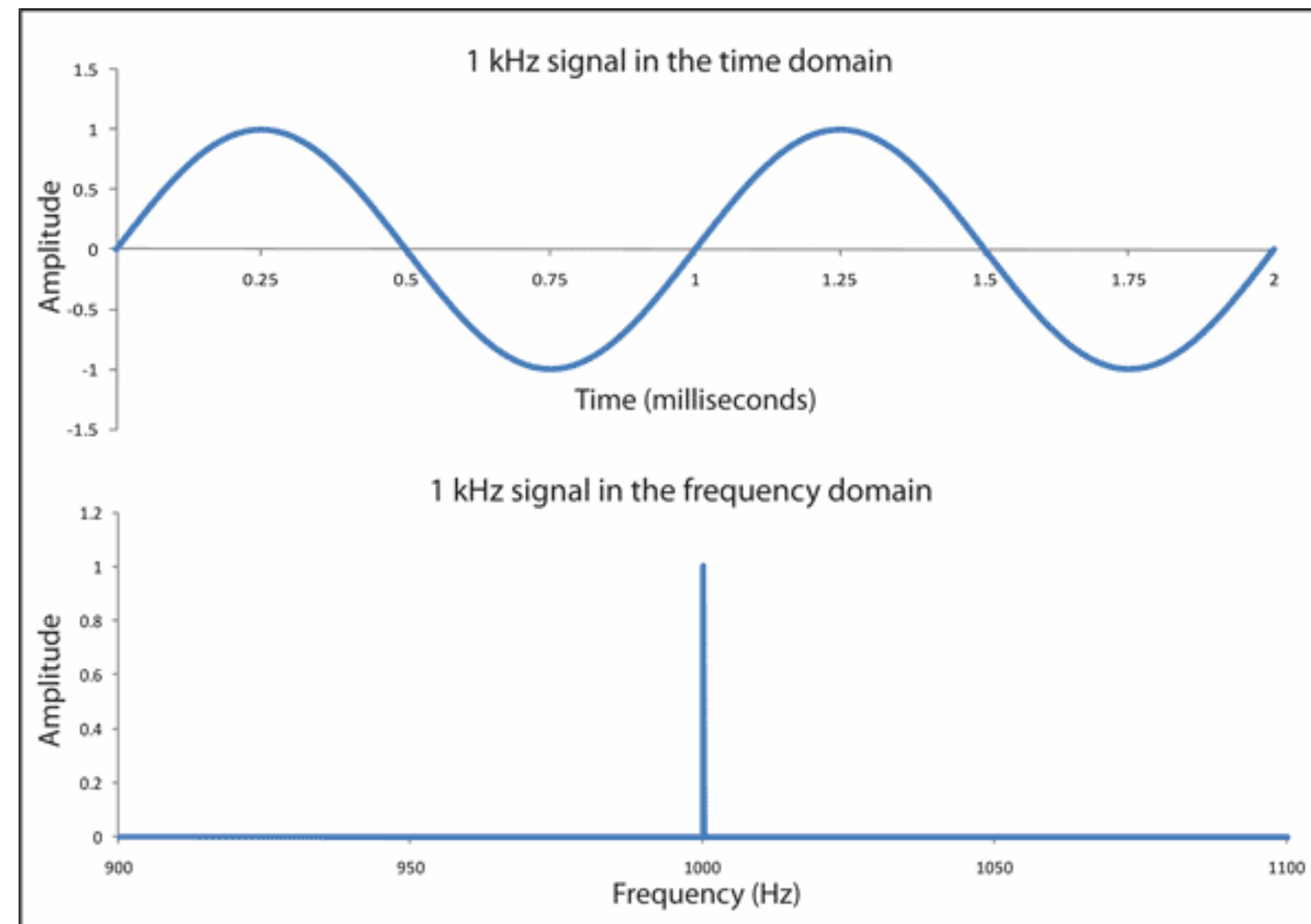
with the identification $o(0) = o(1)$, where $I = [0,1] \subset \mathbb{R}$ is the unit interval, and S^1 is the circle (1–sphere). The functions $\operatorname{Re}(o(t)) = x$ and $\operatorname{Im}(o(t)) = y$ are (orthogonal) *projections* of the circle onto the x and y axes.



A sinusoidal wave $y : \mathbb{R} \rightarrow \mathbb{R}$ is a signal

$$y(t) = \sin(\omega t)$$

where $\omega = 2\pi f$ is the (*angular*) *frequency*. It is a monochromatic (single-frequency) wave.



A (*discrete*) *dynamical system* (X, A) is a space X equipped with a (monoid) action $A = (\mathbb{N}, +)$

$$A \times X \rightarrow X$$

which generates the *time evolution* of X . Equivalently, it is an endomorphism $f : X \rightarrow X$ with

$$n \cdot x = f^n(x).$$

The set

$$\{f^n(x_0) : n \in \mathbb{N}\}$$

is called the *orbit* of a point $x_0 \in X$.

A function $p : X \rightarrow \mathbb{R}$ is called the *output* (or *observation*) *map* of the dynamical system (X, A) , and $y = p(x)$ an *output*.



Discretizing the oscillator

Digital audio is a sequence of amplitudes, $y_n \in [-1,1]$ ¹, quantized to a bit depth, and sampled at a rate f_s .

The discrete oscillator is evaluated at points $t_n = n/f_s$:

$$y_n = \sin(2\pi f \cdot n/f_s) = \sin(2\pi f/f_s \cdot n) = \sin(2\pi\Omega \cdot n)$$

where $\Omega = f/f_s$ is the fraction of a cycle progressed per sample.² Now, let $x_n = n\Omega$, then

$$x_n = x_{n-1} + \Omega$$

$$y_n = \sin(2\pi x_n).$$

Restricting to S^1 gives Essl's eq. (3), $x_n = x_{n-1} + \Omega \mod 1$.³ As a dynamical system, $X = S^1$ and $f = +\Omega \mod 1$ and $p(\cdot) = \sin(2\pi\cdot)$.

¹We'll focus on discretizing the domain, here; in practice, the codomain $[-1,1]$ is also discretized, using floating point arithmetic.

²E.g., with $f = 1kHz$ and $f_s = 44.1kHz$, $\Omega \approx 0.023$.

³"Modding out" here is known in audio as *phase wrapping*.

A *sinusoidal oscillator* (S^1, f) is a discrete dynamical system whose evolution $f: S^1 \rightarrow S^1$ is

$$x_n = x_{n-1} + \Omega \mod 1$$

with output

$$y_n = \sin(2\pi x_n)$$

A general (not-necessarily sinusoidal) oscillator can be written (Essl, eq. 2)

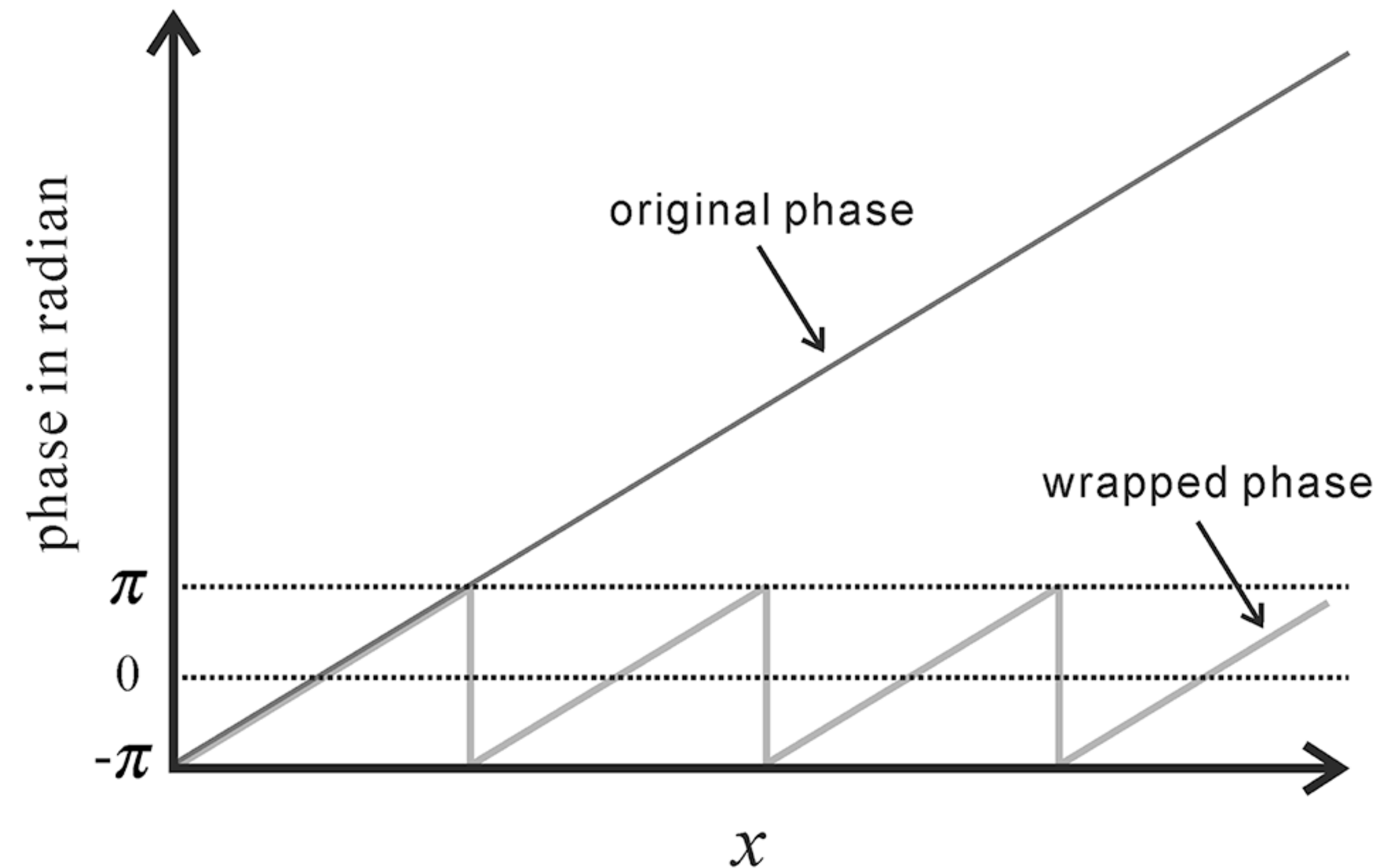
$$\underbrace{y_n}_{\text{Time Series}} = \underbrace{p}_{\text{Projection}} \left(\underbrace{x_n = f(x_{n-1}) \overbrace{\mod 1}^{\text{Circle Topology}}}_{\text{Iterative Phase Function}} \right)$$

where $f: S^1 \rightarrow S^1$ is a circle map. This form decouples the projection and phase update functions.¹

¹N.b., if we change the projection function for the oscillator above to the identity, $p = id$, we obtain a *sawtooth wave*. Conversely, if we change the phase update f to $x_n = x_{n-1} + \Omega + (k/2\pi)\sin(2\pi x_{n-1})$, we get *nonlinear feedback frequency modulation*. $k < 1$ locks to rational pitches; $k > 1$ can go chaotic.

Questions: What is the “mod 1” in Essl’s definition of the discrete sinusoidal oscillator doing?

How does it help us generalize to other types of oscillators?



Answer: it restricts our phase function to live on the circle¹:

$$S^1 = [0,1) = \mathbb{R}/\mathbb{Z}$$

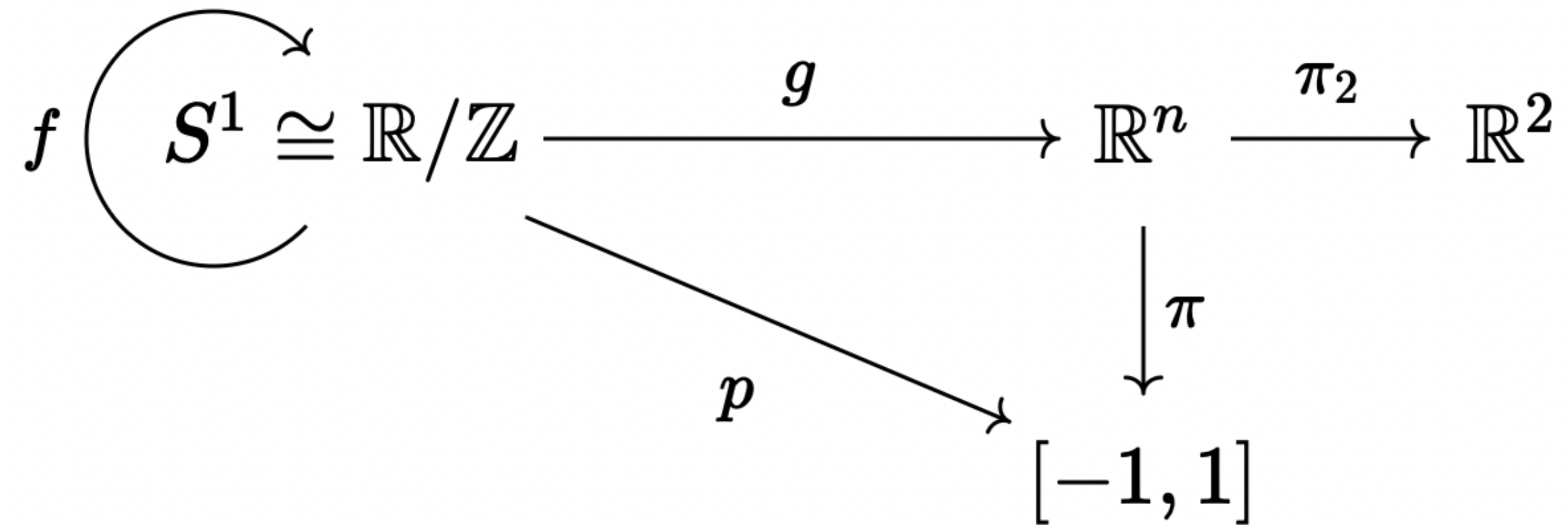
Essl's insight: sinusoids already live on the circle, whereas other types of oscillators, which can become unstable, don't necessarily.

Since S^1 is *compact*, restricting to it stabilizes dynamics, in that orbits stay bounded, no matter what f is.

We can also now parameterize our phase function as processes on closed loops.

¹ $\mathbb{R}/\mathbb{Z}$ is read “ $\mathbb{R}$ mod $\mathbb{Z}$ ”. “Mod 1” is the quotient map $q : \mathbb{R} \rightarrow \mathbb{R}/\mathbb{Z}$ on points, and the universal cover of S^1 ; on functions it induces *periodization* $h(t) \mapsto (h * \mathbb{I})(t) = \sum_k h(t - k)$, which is dual to sampling.

This diagram summarizes the setup:



$X = S^1$ is the state space; g is a continuous map, the *geometric realization*, into some higher-dimensional ambient space; π_2 is a plotting function; and p and π are projection/output/observation maps, such that the triangle *commutes*:

$$p = \pi \circ g$$

The factorization of p allows one to *deform* (vary) g while keeping $f: S^1 \rightarrow S^1$ fixed.

Essl goes on to describe more complex types of oscillators obtained by changing either (or both) of the phase and projection functions:

Oscillator	Phase update $f(x)$ (mod 1)	Projection p	What changed	§
Sine	$x + \Omega$	$\sin(2\pi x)$	—	3.2
Feedback FM (sine circle map)	$x + \Omega + \frac{k}{2\pi} \sin(2\pi x)$	$\sin(2\pi x)$	f	3.3
Deformed carrier	$x + \Omega$	$\pi \circ g$	p	6.1
Feedback FM on a deformed carrier	$x + \Omega + \frac{k}{2\pi} \sin(2\pi x)$	$\pi \circ g$	f, p	6.2
Deformed modulator	$x + \Omega + H p_1(x)$	p_0	the sin inside f	7
Cascade ($i = 0, \dots, N$)	$x^i + \Omega + H^i p_{i+1}(f_i(x^i, x^{i+1}, \omega_m^i))$	p_0	iterate	7.1

In this example, f and Ω are fixed and g is deformed (thus p varies); the result is a fixed pitch with changing timbre.

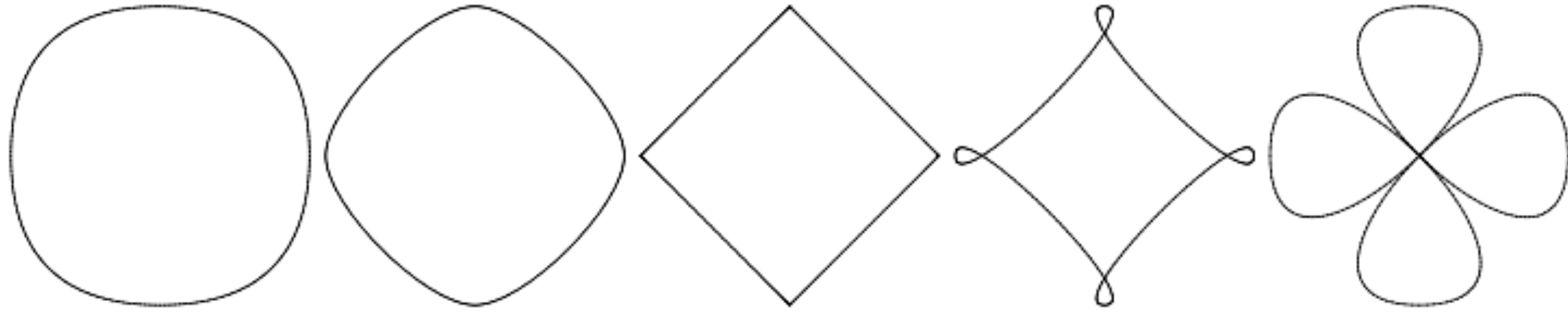


Figure 3: Closed loop tensioned Catmull-Rom splines with four points in a diamond arrangement. $\tau = -1, 0, 1, 2, 5$ from left to right. The center configuration corresponds to a linear connection between control point positions.

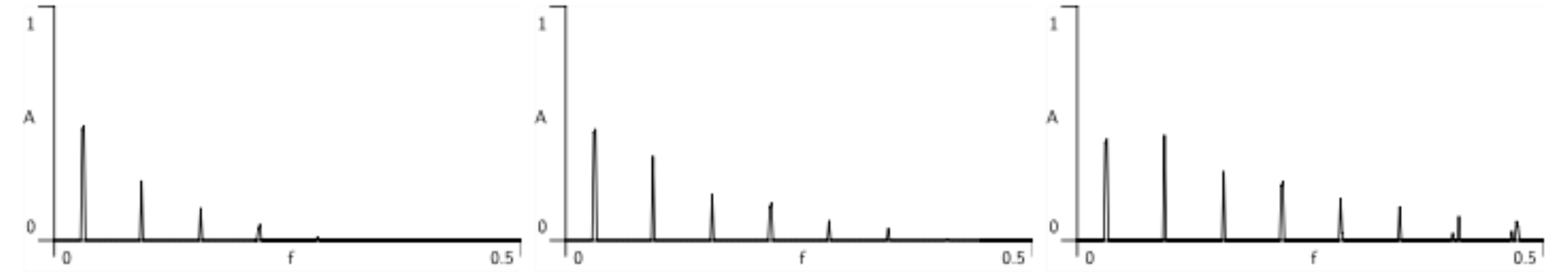


Figure 6: Spectra for the diamond shaped spline for $\tau = -1$, $\tau = 1$ and $\tau = 5$ with $\Omega = 0.03141593$ (corresponding to 1385.4 Hz at 44 100 Hz sampling rate.).

Some potential discussion questions:

- What are some interesting geometric realizations g , other than the spline-based ones that Essl provides?
- (How) can we predict the change in the spectrum based on how g is deformed?
- How might things change if (X, f) were an arbitrary dynamical system, i.e. not an oscillator?

References:

- Georg Essl, *Deforming the Oscillator: Iterative Phases over Parameterizable Closed Paths*, DAFx 2022